

"Build a moving Robot using Arduino" by Sudar Muthu

Days 1 & 2

- **Brief introduction to robotics**
 - Basic concepts
- **Getting to know the contents of the kit**
- **Introduction about Arduino**
 - Why Arduino
 - What is Arduino
 - Setting up Arduino Environment (if not already done)
 - Writing and uploading sketches to Arduino
 - Using external libraries
- **Controlling external devices using Arduino**
- **Introduction to batteries**
- **Introduction about Motors**
 - DC Motors
 - Stepper Motors
- **Controlling DC motors using Arduino**
- **H Bridge**
 - How it works
 - Setting up H bridge
- **Assembling the bot**
 - Writing Arduino code to control the H Bridge
- **Making your bot move**
 - Controlling its direction
 - Adding additional logic to steer the bot
- **Introduction to IR**
 - How IR works
 - Interfacing IR with Arduino
 - Using IR to detect obstacles
 - Teaching the bot how to avoid obstacles
- **Optional Topics**
 - Making the bot follow a line
 - Replacing batteries with solar panels
- **Future ideas**
 - Replacing IR with Ultrasound
 - Controlling bots using Android phones
 - Making it fully autonomous

Caution: All sessions are highly interactive & hands-on with hardware